Http://www.czxhauto.com

### Changzhou Xionghua Tongtai Automation Equipment Co., Ltd



# User's Guide XHPQ Series

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## The XHPQ software installation and use

Before you install the software, please first build a folder and the name is XHPQ in the system disk of your computer.



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The click to install the software .
Natrix Running Fountain Program Software     Sequence Matrix Fountain Program Software     Max. Step OutPutGroups Max. Output X0Start x1Start x2Start x3Start CurrentStep WorkMode HoldTime CommunicatePort     12796   4 *16= 64   0   0   0   +   1   -   0   0   1   -
ProgramSteps 0 8000 CorrespondingSetting F1 Cd00Cd4: 00000 40   DowmLoad UpLoad SaveFile user1 LoadFile user1.pqs   OutPut Y000Y255 Control Exit
000   014   028   042   056   070   084   098   112   126   140   154   168   182   196   210     001   015   029   043   057   071   085   099   113   127   141   155   169   183   197   211   0     002   016   030   044   058   072   086   100   114   128   142   156   170   184   198   212   To     003   017   031   044   058   072   086   100   114   128   142   156   170   184   198   212   To     004   018   032   046   060   074   088   102   116   130   144   158   172   186   200   214   All     005   019   033   047   081   075   090   104   118   132   146   160   174   188   202   216   4ll  <
x4Start x5Start x7Start 0 0 0 0 CommunicationPortState CommunicationNumbers CommunicationTime

We are not familiar with your computer system, so you can try to install. If you can not install the software, tell us, we will try to solve that for you,

The english version instruction:

Note: If you want to change the parameter, you need select the area with the mouse.



like

1.Current step: the work step (max. Step is 12796),

2.**X0 Start~X7Start** :the input signal( For you XO Start is enough), the user can choose which step the program will start from.

- 3.Work Mode: 0,1,2,3,4,5
  - 0,1,2,3 : time unit( 0- 0.1s, 1-1s, 2-1min, 3-0.02s)
  - 4: Jump/cycle instruction
  - 5: stop instruction
- 4. **HoldTime:** the working time = time unit \* HoldTime

When the work mode is 4, the HoldTime will become JumpStep.

5. JumpStep: which step you want to the program cycle from.( for you, the jump step is 1)

Tel: 86-519-86960058 86968907 Email: XHautomation@hotmail.com

6. Output Y000-Y225 control: You can choose the output points in every step.

7. **DownLoad:** When you finish all program, click Download, then the program will write into the controller.

#### 8. Upload: click upload, then the program in the controller will be read out on the softare.

**9.** SaveFile: when you finish all program, you can click SaveFile, then the control file will be save in your computer( you can give it a name you like). When you want to use the program, you can click LoadFile, then the control file will be read, and you can change it.

#### The programmable cable connects the controller and the computer



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